

o t₁ te p₁ op t₁ n su₁ t rn t₁ y nor s₁ roup n s₁ H n₁ propos
 ou₁ oup₁ sto₁ st₁ vo ut on₁ i₁ o₁ or n₁ y₁ u s₁ v₁ our tr₁ / tor s₁ t₁ n₁
 n₁ ross poss₁ su₁ roup or₁ t on sso₁ t₁ t₁ t rn t₁ y so₁ nor s₁ nov₁ t₁
 o t₁ s₁ o₁ s₁ n t₁ t ns on r₁ t₁ t₁ n t₁ o op₁ t₁ n t₁ vo v₁ n so₁
 n t₁ or₁ n t₁ poss₁ t₁ on t₁ or₁ n u₁ nst₁ t₁ s₁ t₁ n t₁ n₁ v₁ u s₁ t₁ y tor₁
 n₁ tor₁ v₁ our st t₁ n₁ s₁
 In s₁ t on₁ ntro u₁ t₁ not on o₁ t₁ y tor n₁ tor s st₁ t₁ t o₁ sts₁ t₁ n ot₁
 t₁ ps₁ o o₁ n₁ t₁ t₁ tr tur s₁ In s₁ t on₁ pr s nt t₁ o₁ n₁
 n n₁ ss o₁ ts₁ n₁ s₁ s o₁ t₁ t o₁ n t on o₁ ur n₁ nst₁ t₁ pro ss₁
 qu t₁ o₁ on n₁ t y tor n₁ tof₁ n₁ s₁ n t₁ o o₁

v r t o s p p ss y—oup n t n t os n y u s st s u ur n nst
 t s n tur r t un or s t r su t n n o su s ts or ty
 n r s ty t on n r ty n r s n t on s o urs n t oup n
 t n n y u s s tron r ort n tor v r st n ort ty tor v r s u
 nst t s s ount r ntut v t rst s t sn n y u s r s n p r s
 n nt t or p t ss p t on t on o n t ons o s tr s to
 v op us n p r s oup n o ty tor n tor v r s s pot nt n s
 or r t n v r t ross popu t ons

It s t us r son to postu t t t n t t t t

o ons, r n vo ut, on qu t, on, or **A.t** E s ssu to vo v n p n nt
 t ou s on t, on p n nt on t, urr nt n t or so s on t, on on
 r t urr nt su stru tur s orr t ov r t, o r t, r t, n
 o ou pro t str ut, on, or, utur n t or vo ut, on on t, on on ts urr nt
 stru tur s

$$P_{\delta t}.A.t.\delta t|A.t,$$

t s nou, to sp t s p t v u **E.A.t.\delta t|A.t** tr ont n n pro
 t s ro s n r t n p n nt r qu v n s tr v,
 s, n **E.A.t.\delta t|A.t** _B **B**_P**P**_{δt}.**B|A.t**, n

$$P_{\delta t}.B|A.t \begin{matrix} N-1,N \\ \triangleright \end{matrix} W_{i,i}^{(B)_{i,i}} - W_{i,i}^{1-(B)_{i,i}}, \\ i=i,i=i+1$$

r **W** **E.A.t.\delta t|A.t** H n s sp our o or t, sto st n t or
 vo ut, on v,

$$E.A.t.\delta t|A.t \quad A.t.\delta tF.A.t,X.t,$$

v s **δt** → H r t, r tr v u un t, on **F** s s tr : t, s ro on
 n su t, t nts or t, n s r n r t

$$F.A.t,X.t - A.t \circ \{\text{Death rates}\} \cdot 1 - A.t \circ \{\text{Birth rates}\}.$$

tr s po ou ons, r t, on, r l o t, r r no st n u s n v u s t, n
 t n ust nv r nt un r n p r ut t, on o t, v r t, s o or p **Q**
 s n **N** × **N** p r ut t, on tr t, n ust v

$$F.A,X \quad Q^T.F.Q.A.Q^T,Q.X.Q, \text{ or } A,X,$$

s s not s r str t y s t pp rs For s nvo v n po no s or H r pro u ts
 o po no s n **A** s t s t, s r str t, on In GH t, s s tr su st r t o
 n ppro s

p n n **F** upon **X** s r t, s n t ou oup s t, s st v n n
 o op t s nt on n t ntroo s n **F** s r rFF **F**

sur n t s r t t n t orr spon n p rs o v rt st t s o s t n

Consider the inner product $\langle \cdot, \cdot \rangle$ on $\mathbb{R}^n$ defined by $\langle \mathbf{x}_1, \mathbf{x}_2 \rangle = \mathbf{x}_1^T \mathbf{A} \mathbf{x}_2$ for

$$\mathbf{A} = \begin{bmatrix} p & -q \\ -q & p \end{bmatrix}, \quad p > q > 0.$$

Find the eigenvalues and eigenvectors of $\mathbf{A}$. It is easy to see that $\mathbf{A}$ is symmetric.

$$\mathbf{A}^T = \mathbf{A} = \begin{bmatrix} p & -q \\ -q & p \end{bmatrix}.$$

Consider the matrix $\mathbf{D} = \begin{bmatrix} d_1 & 0 \\ 0 & d_2 \end{bmatrix}$ where $d_1, d_2 > 0$. The eigenvalues of $\mathbf{D}$ are d_1, d_2 with corresponding eigenvectors $\begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix}$. The eigenvalues of $\mathbf{A}$ are $\pm \sqrt{p^2 + q^2}$ with corresponding eigenvectors $\begin{bmatrix} p \\ q \end{bmatrix}, \begin{bmatrix} -q \\ p \end{bmatrix}$.

Since $\mathbf{A}$ is symmetric, it is orthogonally diagonalizable. That is, there exists an orthogonal matrix $\mathbf{Q}$ such that

$$\mathbf{Q}^T \mathbf{A} \mathbf{Q} = \mathbf{D}.$$

Let $\mathbf{Q} = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$. Its columns are orthonormal vectors $\mathbf{q}_1, \mathbf{q}_2$ such that

$$\mathbf{A} \mathbf{q}_1 = \lambda_1 \mathbf{q}_1, \quad \mathbf{A} \mathbf{q}_2 = \lambda_2 \mathbf{q}_2.$$

For $\mathbf{q}_1 = \begin{bmatrix} \cos \theta \\ \sin \theta \end{bmatrix}$, we have $\mathbf{A} \mathbf{q}_1 = \begin{bmatrix} p \cos \theta - q \sin \theta \\ -q \cos \theta + p \sin \theta \end{bmatrix} = \lambda_1 \begin{bmatrix} \cos \theta \\ \sin \theta \end{bmatrix}$. This gives the system of equations $(p - \lambda_1) \cos \theta - q \sin \theta = 0$ and $-q \cos \theta + (p - \lambda_1) \sin \theta = 0$. For $\mathbf{q}_2 = \begin{bmatrix} -\sin \theta \\ \cos \theta \end{bmatrix}$, we have $\mathbf{A} \mathbf{q}_2 = \begin{bmatrix} -p \sin \theta - q \cos \theta \\ q \sin \theta + p \cos \theta \end{bmatrix} = \lambda_2 \begin{bmatrix} -\sin \theta \\ \cos \theta \end{bmatrix}$. This gives the system of equations $(p + \lambda_2) \sin \theta + q \cos \theta = 0$ and $q \sin \theta + (p + \lambda_2) \cos \theta = 0$.

$$\lambda_{\pm} = \pm \sqrt{p^2 + q^2}.$$

5. Projections

Here we present some suggestions on the output structure of the
 overall transformation. The structure of the output is so
 that the projections to the structure of the output are
 to the structure of the output.

$$A \rightarrow P_B A \quad A, B B$$

For not to be from us, the projection is A, B $A_{ij} B_{ij}, A$ A, B
 the structure of the output is B, B A, B A, B A, B
 the structure of the output is A, B A, B A, B A, B
 the structure of the output is A, B A, B A, B A, B

$$1 \rightarrow \frac{1}{n-1} 1,$$

the structure of the output is A, B A, B A, B A, B

$$R, A \quad P_1, A.$$

the structure of the output is A, B A, B A, B A, B

the structure of the output is A, B A, B A, B A, B

the structure of the output is A, B A, B A, B A, B

the structure of the output is A, B A, B A, B A, B

the structure of the output is A, B A, B A, B A, B

$$A, t \quad R, A, t \quad S, A, t \quad - E, t$$

$$\begin{aligned}
& \mathbf{p} = \mathbf{n} \mathbf{s} \mathbf{n} \mathbf{o} \mathbf{r} \quad , \quad , \quad \mathbf{n} \mathbf{v} \mathbf{t} \mathbf{o} \mathbf{r} \mathbf{s} \quad \mathbf{t} \mathbf{t} \mathbf{n} \quad \delta \mathbf{t} \rightarrow \mathbf{e} \quad \mathbf{o} \mathbf{t} \mathbf{n} \mathbf{t} \quad \mathbf{t} \mathbf{r} \mathbf{n} \mathbf{s} \mathbf{t} \mathbf{s} \mathbf{s} \mathbf{t} \\
& \mathbf{p} = -\mathbf{p} \mathbf{e} - \varphi \cdot \|\mathbf{u}\| \quad \omega \cdot \mathbf{e} = -\mathbf{p} \varphi \cdot \|\mathbf{u}\| \quad , \\
& \mathbf{u} = \mathbf{d} \mathbf{f} \mathbf{x}^* - \mathbf{p} \mathbf{N} \mathbf{D} \cdot \mathbf{u} .
\end{aligned}$$

For $\mathbf{p} = \mathbf{s} \mathbf{t} \varphi \cdot \|\mathbf{u}\|$, $- \mathbf{t} \mathbf{n} \cdot \frac{\|\mathbf{u}\| - \mathbf{e}}{\mu} / \mathbf{r} \mathbf{e} \mathbf{e} , \mu > \mathbf{e}$. $\mathbf{o} \mathbf{s} \mathbf{n} \mathbf{s} \mathbf{o} \mathbf{t} \mathbf{t} \varphi$
 $\mathbf{s} \mathbf{t} \mathbf{s} \mathbf{r} \mathbf{p} \mathbf{s} \mathbf{s} \mathbf{r} \mathbf{s} \|\mathbf{u}\| \mathbf{n} \mathbf{r} \mathbf{s} \mathbf{s} \mathbf{t} \mathbf{r} \mathbf{o} \mathbf{u} \mathbf{e} \mathbf{n} \mathbf{s} \mathbf{u} \mathbf{t} \mathbf{v} \mathbf{u} \mathbf{s} \mathbf{n} \mathbf{u} \mathbf{r}$
 $\mathbf{s} \mathbf{o} \mathbf{u} \mathbf{t} \mathbf{o} \mathbf{n} \mathbf{s} \mathbf{o} \mathbf{s} \mathbf{t} \mathbf{t} \mathbf{t} \mathbf{s} \mathbf{s} \mathbf{s} \mathbf{t} \mathbf{s} \mathbf{p} \mathbf{o} \mathbf{s} \mathbf{s} \mathbf{s} \mathbf{p} \mathbf{r} \mathbf{o} \mathbf{r} \mathbf{t} \mathbf{s}$

6. Conclusion

$\mathbf{s} \mathbf{o} \mathbf{s} \mathbf{s} \mathbf{o} \mathbf{t} \mathbf{t} \mathbf{n} \mathbf{n} \mathbf{v} \mathbf{u} \mathbf{s} \mathbf{o} \mathbf{r} \mathbf{n} \mathbf{n} \mathbf{q} \mathbf{u} \mathbf{r} \mathbf{u} \mathbf{t} \mathbf{n}$
 $\mathbf{t} \mathbf{r} \mathbf{t} \mathbf{y} \mathbf{t} \mathbf{o} \mathbf{n} \mathbf{n} \mathbf{t} \mathbf{o} \mathbf{r} \mathbf{t} \mathbf{n} \mathbf{n} \mathbf{s} \mathbf{r} \mathbf{o} \mathbf{u} \mathbf{p} \mathbf{p} \mathbf{r} \mathbf{s} \mathbf{n} \mathbf{o} \mathbf{o} \mathbf{p} \mathbf{t} \mathbf{n}$
 $\mathbf{s} \mathbf{o} \mathbf{u} \mathbf{p} \mathbf{t} \mathbf{r} \mathbf{t} \mathbf{y} \mathbf{e} \mathbf{o} \mathbf{s} \mathbf{o} \mathbf{n} \mathbf{v} \mathbf{r} \mathbf{n} \mathbf{t} \mathbf{o} \mathbf{t} \mathbf{n} \mathbf{o} \mathbf{r} \mathbf{n}$
 $\mathbf{o} \mathbf{n} \mathbf{s} \mathbf{r} \mathbf{v} \mathbf{t} \mathbf{y} \mathbf{v} \mathbf{o} \mathbf{u} \mathbf{s} \mathbf{n} \mathbf{o} \mathbf{s} \mathbf{t} \mathbf{r} \mathbf{o} \mathbf{s} \mathbf{s} \mathbf{p} \mathbf{o} \mathbf{p} \mathbf{u} \mathbf{t} \mathbf{o} \mathbf{n} \mathbf{n} \mathbf{r} \mathbf{n} \mathbf{o} \mathbf{n} \mathbf{s} \mathbf{t} \mathbf{t} \mathbf{o} \mathbf{u}$
 $\mathbf{t} \mathbf{r} \mathbf{o} \mathbf{s} \mathbf{o} \mathbf{p} \mathbf{s} \mathbf{t} \mathbf{u} \mathbf{t} \mathbf{o} \mathbf{n} \mathbf{s} \mathbf{p} \mathbf{r} \mathbf{t} \mathbf{t} \mathbf{o} \mathbf{u} \mathbf{r} \mathbf{n} \mathbf{s} \mathbf{o} \mathbf{r} \mathbf{n} \mathbf{v} \mathbf{u} \mathbf{s} \mathbf{r} \mathbf{n} \mathbf{o} \mathbf{t} \mathbf{t} \mathbf{n}$
 $\mathbf{o} \mathbf{t} \mathbf{t} \mathbf{r} \mathbf{n} \mathbf{s} \mathbf{t} \mathbf{n} \mathbf{s} \mathbf{t} \mathbf{o} \mathbf{s} \mathbf{t} \mathbf{v} \mathbf{r} \mathbf{s} \mathbf{o} \mathbf{n} \mathbf{s} \mathbf{o} \mathbf{t} \mathbf{o} \mathbf{r} \mathbf{r} \mathbf{r} \mathbf{s} \mathbf{o} \mathbf{o} \mathbf{n} \mathbf{t} \mathbf{o} \mathbf{r} \mathbf{s}$
 $\mathbf{n} \mathbf{s} \mathbf{o} \mathbf{o} \mathbf{o} \mathbf{n} \mathbf{o} \mathbf{s} \mathbf{o} \mathbf{s} \mathbf{s} \mathbf{r} \mathbf{t} \mathbf{t} \mathbf{t} \mathbf{v} \mathbf{r} \mathbf{n} \mathbf{t} \mathbf{t} \mathbf{t} \mathbf{u} \mathbf{s} \mathbf{s} \mathbf{n} \mathbf{s} \mathbf{o} \mathbf{n} \mathbf{o} \mathbf{r} \mathbf{s} \mathbf{r} \mathbf{q} \mathbf{u} \mathbf{r}$
 $\mathbf{r} \mathbf{s} \mathbf{n} \mathbf{r} \mathbf{p} \mathbf{o} \mathbf{s} \mathbf{o} \mathbf{n} \mathbf{p} \mathbf{o} \mathbf{p} \mathbf{u} \mathbf{t} \mathbf{o} \mathbf{n} \mathbf{s} \mathbf{o} \mathbf{r} \mathbf{s} \mathbf{t} \mathbf{r} \mathbf{y} \mathbf{n} \mathbf{p} \mathbf{r} \mathbf{t} \mathbf{p} \mathbf{r} \mathbf{n} \mathbf{s} \mathbf{n}$
 $\mathbf{v} \mathbf{u} \mathbf{t} \mathbf{s} \mathbf{B} \mathbf{u} \mathbf{t} \mathbf{r} \mathbf{n} \mathbf{s} \mathbf{t} \mathbf{t} \mathbf{t} \mathbf{r} \mathbf{n} \mathbf{s} \mathbf{n} \mathbf{t} \mathbf{s} \mathbf{n} \mathbf{o} \mathbf{o} \mathbf{u} \mathbf{s} \mathbf{t} \mathbf{r} \mathbf{s} \mathbf{u} \mathbf{r} \mathbf{o} \mathbf{u} \mathbf{p} \mathbf{s}$
 $\mathbf{o} \mathbf{n} \mathbf{v} \mathbf{r} \mathbf{s} \mathbf{v} \mathbf{s} \mathbf{n} \mathbf{n} \mathbf{f} \mathbf{n} \mathbf{t} \mathbf{v} \mathbf{o} \mathbf{u} \mathbf{t} \mathbf{n} \mathbf{o} \mathbf{u} \mathbf{p} \mathbf{s} \mathbf{s} \mathbf{t} \mathbf{s} \mathbf{s} \mathbf{n}$
 $\mathbf{t} \mathbf{n} \mathbf{o} \mathbf{r} \mathbf{s} \mathbf{t} \mathbf{t} \mathbf{o} \mathbf{r} \mathbf{s} \mathbf{t} \mathbf{n} \mathbf{s} \mathbf{o} \mathbf{t} \mathbf{s} \mathbf{v} \mathbf{n} \mathbf{t} \mathbf{o} \mathbf{u} \mathbf{t} \mathbf{r} \mathbf{n} \mathbf{t} \mathbf{s} \mathbf{n} \mathbf{o} \mathbf{r} \mathbf{n} \mathbf{t} \mathbf{r} \mathbf{s}$
 $\mathbf{E} \mathbf{v} \mathbf{n} \mathbf{t} \mathbf{s} \mathbf{t} \mathbf{o} \mathbf{s} \mathbf{t} \mathbf{n} \mathbf{s} \mathbf{o} \mathbf{r} \mathbf{A} \mathbf{t} \mathbf{r} \mathbf{r} \mathbf{p} \mathbf{t} \mathbf{r} \mathbf{n} \mathbf{s} \mathbf{t} \mathbf{n} \mathbf{s} \mathbf{o} \mathbf{r}$
 $\mathbf{t} \mathbf{o} \mathbf{u} \mathbf{n} \mathbf{t} \mathbf{o} \mathbf{n} \mathbf{n} \mathbf{t} \mathbf{r} \mathbf{o} \mathbf{n} \mathbf{o} \mathbf{t} \mathbf{n} \mathbf{s} \mathbf{s} \mathbf{s} \mathbf{t} \mathbf{t} \mathbf{t} \mathbf{s} \mathbf{p} \mathbf{r} \mathbf{o}$
 $\mathbf{n} \mathbf{r} \mathbf{n} \mathbf{n} \mathbf{s} \mathbf{o} \mathbf{s} \mathbf{n} \mathbf{s} \mathbf{t} \mathbf{y} \mathbf{p} \mathbf{n} \mathbf{n} \mathbf{s} \mathbf{t} \mathbf{r} \mathbf{n} \mathbf{t} \mathbf{y} \mathbf{o} \mathbf{s} \mathbf{s} \mathbf{s} \mathbf{s} \mathbf{n} \mathbf{e} \mathbf{I} \mathbf{n} \mathbf{s} \mathbf{u}$
 $\mathbf{s} \mathbf{s} \mathbf{t} \mathbf{o} \mathbf{r} \mathbf{t} \mathbf{s} \mathbf{r} \mathbf{o} \mathbf{t} \mathbf{n} \mathbf{o} \mathbf{t} \mathbf{t} \mathbf{t} \mathbf{o} \mathbf{s} \mathbf{t} \mathbf{u} \mathbf{n} \mathbf{n} \mathbf{o} \mathbf{t} \mathbf{p} \mathbf{r} \mathbf{t} \mathbf{t} \mathbf{r}$
 $\mathbf{n} \mathbf{s} \mathbf{p} \mathbf{n} \mathbf{v} \mathbf{u} \mathbf{s} \mathbf{o} \mathbf{r} \mathbf{t} \mathbf{y} \mathbf{n} \mathbf{t} \mathbf{o} \mathbf{r} \mathbf{r} \mathbf{t} \mathbf{y} \mathbf{t} \mathbf{y} \mathbf{t} \mathbf{n} \mathbf{u} \mathbf{t} \mathbf{u} \mathbf{r}$
 $\mathbf{s}$

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 Int rn t t s
 rson t ov n n Co o J B r s o t n Ho op n
 so n t or s Ann v o
 Hoo B I us on H rp rCo ns
 B n ro t J Gr CA J nss n E n rs A u ontro o urr nt
 st tus n putur r t ons J s r Jun
 Gr J A ps o o r n str ss C r C r n y rs t
 r ss
 Gr n ro tt rns n v s n E t on
 r J A n Gr n ro Ap r o n s n t r n st o u
 tur ss n t on Dr t su tt