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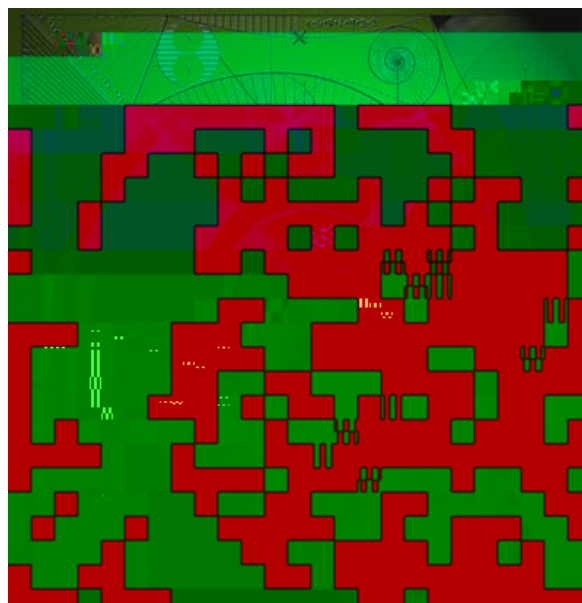
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On Discrimination Algorithms for Ill-Posed Problems with an Application to Magnetic Tomography

by

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A r c

n p pe e po ec c on ec n e o po ed po e . lo c e
e ine ry sep r e n o e e p ce X ey c n e ep ed y ye p ne
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$$n \rho_r = n A_r \rho_r \quad \text{2}$$

of tumours [1]. In [4] the cancer area classification problem is investigated with voxels

study particular nonlinear classes which are obtained from linear classes as intersections of affine halfspaces U_ℓ , $\ell = 1, \dots, n$, i.e.

$$C := \bigcap_{\ell=1}^n U_\ell. \quad (2.2)$$

In this case we can reduce the study of stability of the classification to the stability in the linear case. For smooth classes, i.e. where the boundary of C is a smooth manifold in X , we can locally approximate the general nonlinear classification by a linear classification, such that in this case the stability analysis can also be carried over from the linear to the nonlinear case.

The process of classification is given by the way to achieve a definition of a class C .

Definition 2.1 (Supervised Classification)

Let X be a set, $\mathbf{x}_1^{(1)}, \dots, \mathbf{x}_1^{(N_1)} \in X$ be samples, $C_1 \subset X$ be a subset, $\omega = 1, \dots, N_1$ be target values, $C = X \setminus C_1$ be the complement of C_1 in X , and y be a supervised classification algorithm.

when we study stable classifications in X and how they can be achieved on the images in Y without the inversion of the operator A .

A generic example. As a first step towards the clarification of the situation we first want to consider a special case. We use the singular value decomposition of the operator A , compare [6], i.e. we have an orthonormal basis $\{\phi_\ell \in X, \ell \in \mathbb{N}\}$ in X and an orthonormal basis $\{g_\ell \in Y, \ell \in \mathbb{N}\}$ and a monotonously decreasing sequence $(\mu_\ell)_{\ell \in \mathbb{N}}$ of positive real values such that

$$A\phi_\ell = \mu_\ell g_\ell, \quad A^*g_\ell = \mu_\ell \phi_\ell \quad (2.3)$$

for all $\ell \in \mathbb{N}$. We define a linear stable classification by

$$C_{\ell_1}^{(1)} := \{x : \langle x, \phi_{\ell_1} \rangle \geq \rho\}, \quad C_{\ell_1}^{(-)} := \{x : \langle x, \phi_{\ell_1} \rangle \leq -\rho\}, \quad (2.4)$$

which we call a $n \quad r \quad \rho \quad r \quad n \quad n \quad r \quad n \quad n \quad r \quad \rho \quad r$. Clearly, the distance between $C_{\ell_1}^{(1)}$ and $C_{\ell_1}^{(-)}$ is $2\rho > 0$. For every pair $C_{\ell_1}^{(1)}, C_{\ell_1}^{(-)}$ from the sequence of classes the classification is stable uniformly with respect to $\ell \in \mathbb{N}$.

The images of the classes $C_{\ell_1}^{(1)}, C_{\ell_1}^{(-)}$ under the application of the operator A is given by

$$\begin{aligned} \tilde{C}_{\ell_1}^{(1)} &:= \{y = Ax : \langle x, \phi_{\ell_1} \rangle \geq \rho\}, \\ &= \{y \in A(X) : \langle A^{-1}y, \phi_{\ell_1} \rangle \geq \rho\}, \\ &= \{y \in A(X) : \langle y, (A^{-1})^* \phi_{\ell_1} \rangle \geq \rho\}, \\ &= \{y \in A(X) : \langle y, \frac{1}{\mu_{\ell_1}} g_{\ell_1} \rangle \geq \rho\}, \\ &= \{y \in A(X) : \langle y, g_{\ell_1} \rangle \geq \mu_{\ell_1} \rho\}, \end{aligned} \quad (2.5)$$

and

$$\tilde{C}_{\ell_1}^{(-)} := \{y : \langle y, g_{\ell_1} \rangle \leq -\mu_{\ell_1} \rho\}. \quad (2.6)$$

The distance between the classes $\tilde{C}_{\ell_1}^{(1)}$ and $\tilde{C}_{\ell_1}^{(-)}$ is $2\mu_{\ell_1}\rho$. The distance is depending on $\ell \in \mathbb{N}$ and since the singular values μ_ℓ tend to zero for $\ell \rightarrow \infty$, the stability of the separation of the pairs of classes is no longer uniform in ℓ . We summarize these basic but important observations in the following lemma.

Lemma 2.2 $n \quad r \quad \rho \quad n \quad r \quad \rho \quad r \quad A \quad n \quad r \quad \rho \quad X \quad n \quad Y$
 $n \quad r \quad n \quad r \quad \rho \quad r \quad n \quad n \quad r \quad n \quad n \quad r \quad \rho \quad r$
 $\downarrow \quad \downarrow \quad \downarrow \quad \downarrow \quad \downarrow \quad \downarrow \quad \downarrow \quad \downarrow \quad \downarrow \quad \downarrow \quad \downarrow \quad \downarrow \quad \downarrow \quad \downarrow \quad \downarrow$
 $\rho \quad Y \quad \rho \quad n \quad n \quad \rho \quad n \quad n \quad r \quad n \quad r \quad y \quad \rho \quad r \quad n$

The general case. Next, we consider the general case of a sequence of linear classes $C_1, C_2, C_3, \dots$. Let $v_\ell, \ell \in \mathbb{N}$ be the corresponding vectors in X and $\rho_\ell, \ell \in \mathbb{N}$ be the affine distances. Here, we also assume that the sequence (v_ℓ) does not have a convergent subsequence. Clearly, the classes are given by

$$C_\ell = \{x : \langle x, v_\ell \rangle \geq \rho_\ell\}, \quad \ell \in \mathbb{N}. \quad (2.7)$$

$$\rho_r = \frac{1}{n} \sum_{i=1}^n A_{ii} \rho_r = \rho_r \tag{2.6}$$

We use a calculation similar to (2.5) to show that if $\mathbf{v}_\ell$ is in the range of $\mathbf{A}$, then

$$\tilde{\mathbf{C}}_\ell := \mathbf{A} \mathbf{C}_\ell = \{ \mathbf{y} : \langle \mathbf{y}, (\mathbf{A})^{-1} \mathbf{v}_\ell \rangle \geq \rho_\ell \}. \tag{2.8}$$

With the definition

$$\boldsymbol{\psi}_\ell := (\mathbf{A})^{-1} \mathbf{v}_\ell \tag{2.9}$$

$$n \rho_r = n A_r \rho_r$$

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and with the same argument we also have the slightly more general form of this statement

$$\nabla \cdot \mathbf{P} = r \quad \nabla \cdot \mathbf{A} = r \quad \mathbf{P} = \mathbf{P}_r$$

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3. Static Magnetic Tomography

Here, we collect basic notation and results on static magnetic tomography, for more details we refer to [

$$n \rho_r = n A_r \rho_r$$

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Wannert et.al. In [

$$n \rho_r = n A_r \rho_r$$

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There are two basic options to approach the classification problem from magnetic

$$n \rho_r = n_A \rho_r$$

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Example. As a two-dimensional example for our nonlinear class we consider the space $\mathbb{R}^2$ with two classes C_1, C_2 defined by

$$C_1 := \{\mathbf{j} \in \mathbb{R}^2 : j_1 \geq 0.544 = 48(t)26\}$$

$$\rho_r = \frac{1}{n} \int_{\Omega} \rho_r \, dx = \frac{1}{n} \int_{\Omega} \rho_r \, dx = \rho_r \quad (4.14)$$

for every $L \in \mathbb{N}$. With the area or volume $|\Omega_L^{(L)}|$, respectively, of some set $\Omega_L^{(L)}$ we define

$$\chi_L^{(L)}(\mathbf{x}) := \begin{cases} \frac{1}{|\Omega_L^{(L)}|^{1/2}}, & \mathbf{x} \in \Omega_L^{(L)}, \\ 0, & \text{otherwise.} \end{cases} \quad (4.12)$$

the functions $\chi_L^{(L)}$ are in $L^2(\Omega)$ for $L = 1, \dots, n_L$ and $L \in \mathbb{N}$. Then we have

$$\sum_{L=1}^{n_L} \chi_L^{(L)} = 1 \quad (4.13)$$

We now collect all vectors $\chi_L^{(L)}$ for $L = 1, \dots, n_L$ and $L = 1, 2, 3, \dots$ into one sequence, for which we use the letter $\mathbf{v}$, $k \in \mathbb{N}$.

For the fuel cell application nonlinear classes will naturally appear when the flow through the cell membrane is monitored. For example, the vectors $\chi_L^{(L)}$ can be chosen to be the special basis used for current reconstructions by Wannert and Potthast [22]. Here, the class $C_L^{(L)}$ is the set of all currents which have a component larger than $\rho_L^{(L)}$ along the direction $\chi_L^{(L)} \in L^2(\Omega)$. Good cells are those where we have a homogeneous distribution of the current, which means that all components are larger than some threshold ρ . This corresponds to the nonlinear class C defined in (4.6), which is composed of a sequence of linear classes.

We may choose a hierarchy of finer and finer discretizations to test the homogeneity

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$$n \mathcal{P} \quad r \quad n \quad n \quad A \quad r \quad r \quad \mathcal{P} \quad \mathcal{P}_r$$

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5. On the Ill-Posedness of Fisher's Linear Discriminant for Remote Data

So far we have studied the ill-posedness of classification problems which can be based on linear classification. We have shown that in general linear compact operators map stably separable problems into classifications which are no longer stably separable. However, we have not yet studied a particular algorithm for such classifications.

The task of this section is to investigate a well-known scheme for supervised classification 2.1 known as $r \quad L \quad n \quad r \quad \mathcal{P} \quad r \quad n \quad n$. We will show that the method is also ill-posed in the sense that for an increased number of measurement points the norm of the inverse operators employed by the method become unbounded. As a particular application, we will apply the method to the problem of fuel cell classification and investigate the relationship between different ways to regularize the problem.

$$r \quad L \quad n \quad r \quad \mathcal{P} \quad r \quad n \quad n \quad n \quad j \quad n \quad H$$

Fisher's linear discriminant is not strictly speaking a discriminant but rather a method of $r \quad j \quad n \quad n \quad n \quad y$ of the input space in such a way that we have maximum class separation in the new 0.147034(h)-0.312447(e)-313.123(i)0.21(a)0.245057(m7-0.147034(h)-n)-0.31

$$\|P_r - A_r\|_F \leq \|P - A\|_F \leq \sqrt{r} \|P - A\|_2 \leq \sqrt{r} \epsilon$$

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We will complete this section by a rigorous proof showing that in this case the norm of the inverse

$$\|P_r - A_r\|_{\mathcal{L}(L^2(\Omega))} \leq \|P_r - P_r\|_{\mathcal{L}(L^2(\Omega))} = 0$$

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from which the statement follows. $\square$

Since $W : (C(\Omega)) \rightarrow (C(\Lambda))$ is compact and $W : (C(\Lambda)) \rightarrow (C(\Omega))$ is compact as well, the operator $S_F^{(\cdot)}$ is compact in $(C(\Lambda))$.

A discretization of this operator is achieved by using numerical quadrature for all three of its factors. With nodes z_κ , $\kappa = 1, \dots, M$ in Ω and quadrature weights s_κ we discretize x via z_κ and y via z_κ . Then, the operator $S_F^{(\cdot)}$ is approximated via the matrix

$$\rho_r = \rho|_{\partial\Omega_r} = \rho|_{\partial\Omega} = \rho_r \quad (5.19)$$

uniformly for all $\tilde{M} \in \mathbb{N}$, such that (5.20) is satisfied. We denote an interpolation operator on Λ by $Q^{(M)}$ and assume to have

$$\|Q^{(M)}\psi\| \leq c\|\psi\| \quad (5.20)$$

with some constant c uniformly for $\tilde{M} \in \mathbb{N}$ and a result analogous to (5.18).

The continuous form of the Biot-Savart operator W is given by (3.1). A discretization of W via standard quadrature or via finite integration technique leads to some matrix W^M .

where $\mathbf{w}^{(H)}$ represents the weight vector found by applying Fisher's linear discriminant to H . Then

$$\begin{aligned}\mathbf{w}^{(H)} &\propto \mathbf{B}^\top \mathbf{S}_F^{(\beta)^{-1}} \mathbf{B}^{-1} \mathbf{W} \mathbf{J} \mathbf{m}^{(\beta)} - \mathbf{W} \mathbf{J} \mathbf{m}_1^{(\beta)} \\ &= \mathbf{B}^\top \mathbf{S}_F^{(\beta)^{-1}} \mathbf{m}^{(\beta)} - \mathbf{m}_1^{(\beta)}.\end{aligned}\quad (5.38)$$

It is linked to the classification vector $\mathbf{w}^{(\cdot)}$ in the input space by

$$\mathbf{w}^{(H)} \propto \mathbf{B}^\top \mathbf{w}^{(\beta)}, \quad (5.39)$$

which is a discrete version of (2.9). Classification in the image space given some data H is carried out by calculating $(\mathbf{w}^{(H)})^\top H$. In the state space it is given by

$$(\mathbf{w}^{(\beta)})^\top \beta = (\mathbf{w}^{(\beta)})^\top \mathbf{B}^{-1} H = (\mathbf{w}^{(H)})^\top H, \quad (5.40)$$

which proves the theorem. $\square$

Finally, we need to study the relation between the two regularized versions of Fisher's linear discriminant. The first version uses Tikhonov regularization directly applied to invert $\mathbf{S}_F^{(H)}$, i.e. we calculate

$$\mathbf{R}^{(H)} := \alpha \mathbf{I} + \mathbf{S}_F^{(H)} \mathbf{S}_F^{(H)^{-1}} \mathbf{S}_F^{(H)}, \quad \alpha > 0. \quad (5.41)$$

The regularized version of (5.37) is thus given by

$$\mathbf{w}^{(H)} := \mathbf{R}^{(H)} \mathbf{m}^{(H)} - \mathbf{m}_1^{(H)}. \quad (5.42)$$

The second version applies the discrimination algorithm to the reconstructed coefficients, i.e. it uses

$$\beta^{(\cdot)} := \alpha \mathbf{I} + \mathbf{B}^\top \mathbf{B}^{-1} \mathbf{B}^\top H^{(\cdot)}, \quad \alpha > 0. \quad (5.43)$$

We define $\mathbf{m}_\xi$ as the mean of the $\beta^{(\cdot)}$ for $\mathbf{C}_\xi$ and

$$\mathbf{S}_\xi^{(\beta)} := \frac{1}{|\mathbf{C}_\xi|} \sum_{\beta^{(\omega)} \in \mathbf{C}_\xi} (\beta^{(\omega)} - \mathbf{m}_\xi)(\beta^{(\omega)} - \mathbf{m}_\xi)^\top, \quad (5.44)$$

for $\xi = 1, 2$ and $\mathbf{S}_F^{(\beta)} = \mathbf{S}_1^{(\beta)} + \mathbf{S}^{(\beta)}$ as usual. Then, we calculate

$$\mathbf{S}_F^{(\beta)} = \alpha \mathbf{I} + \mathbf{B}^\top \mathbf{B}^{-1} \mathbf{B}^\top \mathbf{S}_F^{(H)} \mathbf{B}^{-1} \alpha \mathbf{I} + \mathbf{B}^\top \mathbf{B}^{-1}. \quad (5.45)$$

Now, the second version calculates a regularized version of the discrimination vector $\mathbf{w}^{(\beta)}$ by

$$\mathbf{w}^{(\beta)} := \mathbf{S}_F^{(\beta)^{-1}} \mathbf{m}^{(\beta)} - \mathbf{m}_1^{(\beta)}. \quad (5.46)$$

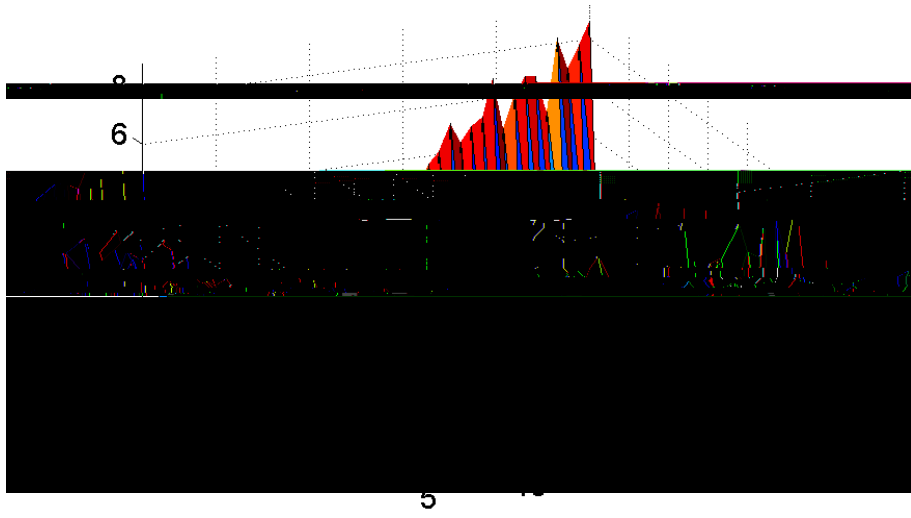
Lemma 5.8

$$\begin{aligned} & \begin{matrix} r & \downarrow & r & n & & r & n & n & \rho^r & r & n \\ r & \rho & y & r & n & \downarrow & n & n & n & n & r & y & n & \rho^r \\ n & & & n & n & n & n & r & \rho & n & n & \rho & r & r & n & r & n & r \end{matrix} \\ & n \quad \rho \rho^r \quad \rho^r \quad y \end{aligned}$$

$$n \rho_r n n A_r r \rho \rho_r$$



F g re e ne d c n n pe o ed on ec o $\beta^{(\omega)}$ o nc on



Figure

