

Early Warning with Calibrated and Sharper Probabilistic Forecasts

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Abstract

Given a nonlinear deterministic model, a density forecast $\hat{p}_t$

ar na ca brat on w. n. not a o. at t. s. D ns t or asts ar
 sa. to b probab st a a brat. an on t. I s ar un of str but.
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 s m s to av b n on b Bross an t s am asur o ow on ntrat
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[illegible]

2 Probabilistic-Forecast Quality

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ar. p. ss. as a so b. n. quant. b. on. n. nt r. va. s. a. t. r. a. Gn. t. n. F. a. Con. n. nt r. va. s. s. ar. a. s. ar. w. a. n. ss. to. var. an. t. s. ns. t. at. a. b. o. a. str but on t. at. s. ar. on. n. tr. at. on. t. two. o. s. an. av. a. f. r. on. n. nt r. va. s. t. an. a. u. m. o. a. str but on t. at. s. ar. spr. a. out. A. so. F. v. a. two. non. sm. tr. str but ons. w. o. t. m. s. m. s. ar. p. r. ou. p. n. on. w. at. t. on. n. v. s.

2.3 Calibration

a. brat on o. ns. t. or. asts. s. a. w. tro. n. sub. t. u. o. t. t. ratur. ta. st. stan. t. at. a. a. brat. or. ast. n. f. s. st. m. stant. a. ount. to. a. orr. t. sp. m. Corra. wanson. prov. a. o. pr. ns. v. surv. o. o. a. stat. st. a. g. t. n. qu. s. or. ass. ss. n. f. a. brat on o. ns. t. or. asts. to. t. m. n. t. un. r. n. f. m. o. s. orr. t. sp. vor. o. Gn. t. n. F. a. str. s. a. s. or. b. prov. n. f. a. a. brat on r. a. wor. t. at. a. m. o. at. sm. o. m. ssp. at on. bro. own. a. brat on nt. o. t. r. m. o. s. a. o. w. ou. b. ass. ss. s. parat. u. p. os. a. probab. t. or. ast. n. f. s. st. m. ssu. s. pr. t. v. str but ons. $\{ \mathbf{x}_t \}_{t=1}^T$ w. t. at. F. n. rat. n. f. pro. ss. ssu. s. a. or. asts $\{ \mathbf{x}_t \}_{t=1}^T$ Gn. t. n. F. a. t. n. n. t. o. ow. n. m. o. s. o. a. brat on.

- s. qu. n. $\{ \mathbf{x}_t \}_{t=1}^T$ s. probab. st. ca. y. ca. brat. r. at. v. to $\{ \mathbf{x}_t \}_{t=1}^T$

$$\subseteq \sum_{t=1}^T t \{ \mathbf{x}_t^{-1} p \} \quad p \quad p \square \quad \leftarrow$$

- s. qu. n. $\{ \mathbf{x}_t \}_{t=1}^T$ s. x. c. r. anc. ca. brat. r. at. v. to $\{ \mathbf{x}_t \}_{t=1}^T$

$$\subseteq \sum_{t=1}^T \mathbf{x}_t^{-1} \{ \mathbf{x}_t \} \quad \mathbf{x} \quad \mathbf{x} \square \square$$

- or. ast. r. s. ar. na. y. ca. brat. r.

$$\mathbf{m} \subseteq \sum_{t=1}^T \mathbf{x}_t \quad \mathbf{m} \subseteq \sum_{t=1}^T \mathbf{x}_t$$

I. w. av. a. t. m. s. r. s. o. obs. rvat. ons. $\mathbf{x}_t$ t. n. t. $\mathbf{x}_t$ s. a. probab. ty. nt. a. trans. or. I. Corra. wanson. D. bo. a. n. o. n. t. o. t. I. s. s. qu. va. nt. to. probab. st. a. brat on. Gn. t. n. F. a. A. v. qua. ns. p. t. on. o. I. st. o. f. r. s. wou. r. v. a. obv. ous. partur. s. re. un. or. t. un. r. n. f. m. o. s. orr. t. sp. an. on. t. $\square$.

Suppose we have a sequence of vectors $\{x_t\}_{t=1}^T$ in $\mathbb{R}^n$.
 The average of these vectors is

$$\bar{x} = \frac{1}{T} \sum_{t=1}^T x_t$$

The variance of these vectors is

$$x_t - \bar{x} = \frac{1}{T} \sum_{t=1}^T x_t$$

For a given $\{x_t\}_{t=1}^T$ to be a stationary process, we need $x_t = \bar{x}$.
 The variance of these vectors is

For a practical purpose, we need to know the variance of these vectors.
 The variance of these vectors is

$$x_t - \bar{x}$$

Gndddd.

with an instantaneous state of

$$^{(t)}x = \frac{1}{N} \sum_{i=1}^N \left\{ \left(x - X_i^{(t)} - \right. \right\}$$

w. r an ar r sp t v ban w t an o s t para t rs os n a or nf to
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t Ba s an o Av ra f g propos b a t r a w a un o b as
orr t on an qua w f ts H r t g nsm b m m b rs ar x an f ab an o
not r pr s nt st n t m o s t nf us nf v r an o s not a ount or
m o m ssp at on

a count on $\mathbf{m}_0$ of $\mathbf{m}$ ssp at on t us rst, not a r or, o past m s
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 or asts w os para t rs an a s t, b a n f into a ount past p r or
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 para t rs ar s t, b, o n f t, m n sat on

$$m_{\sigma>0,\mu} = \frac{1}{T} \sum_{t=1}^T \text{of}_t^{\sigma>0,\mu}(\mathbf{t}) \quad \mathbf{t} | \mathbf{V}_T$$

Verification of runtime assumptions for floating-point matrix multiplication

an¹ t¹ para¹ t¹ rs¹ c¹ an¹ c¹

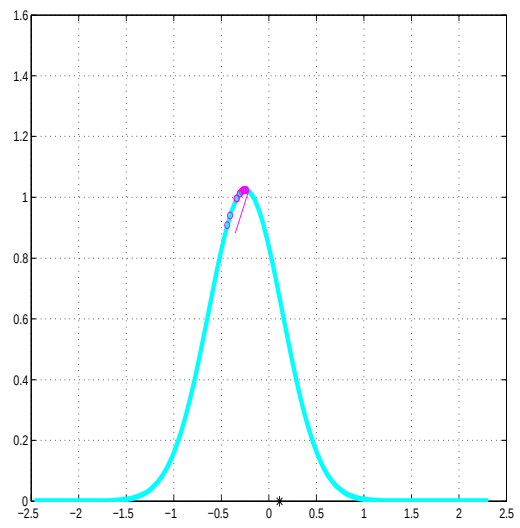
w. n. Dispt t. sr, ut on se mxtur or asts ma st b ss s arp t. an
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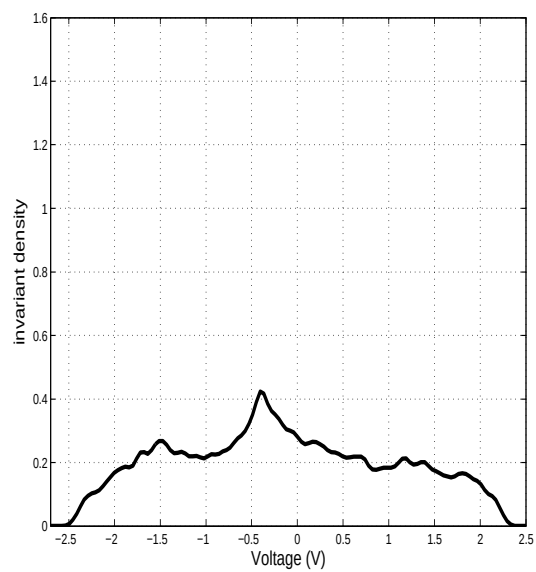
$$\begin{aligned}
 \{ (t) \} - c &\leq \{ (t) \} \leq \{ (t) \} - \{ (t) \} c \\
 &= \{ c^{(t)} \} - c
 \end{aligned}$$

w. r $-\int x$ of x , an $-\int x$ of x , x ar t. ntrop
 an, ross ntrop r sp t v. r or t. n ssar an, su nt on, t ons or
 $\{ (t) \} c$ o. o, ar t at $c \setminus \{ (t) c \}$ an $c \setminus \{ (t) \}$ r sp .
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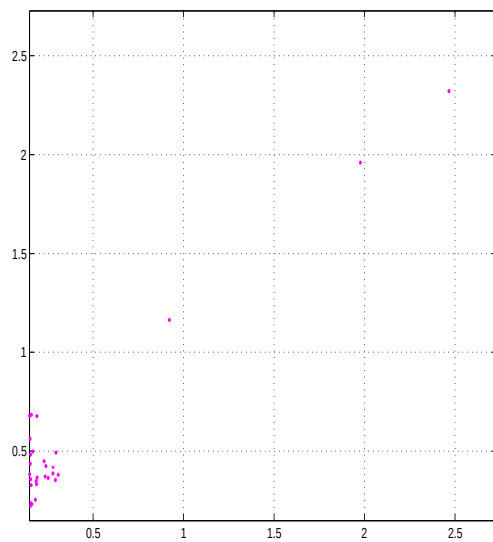
It s not obv ous w at t. to t. mxtur s on a brat on pt t. at n u nF
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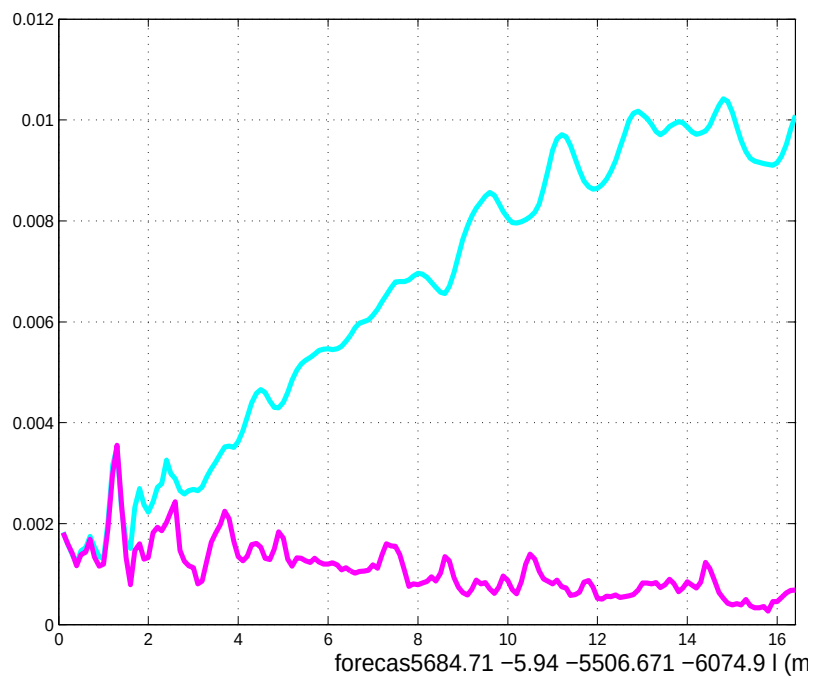
□

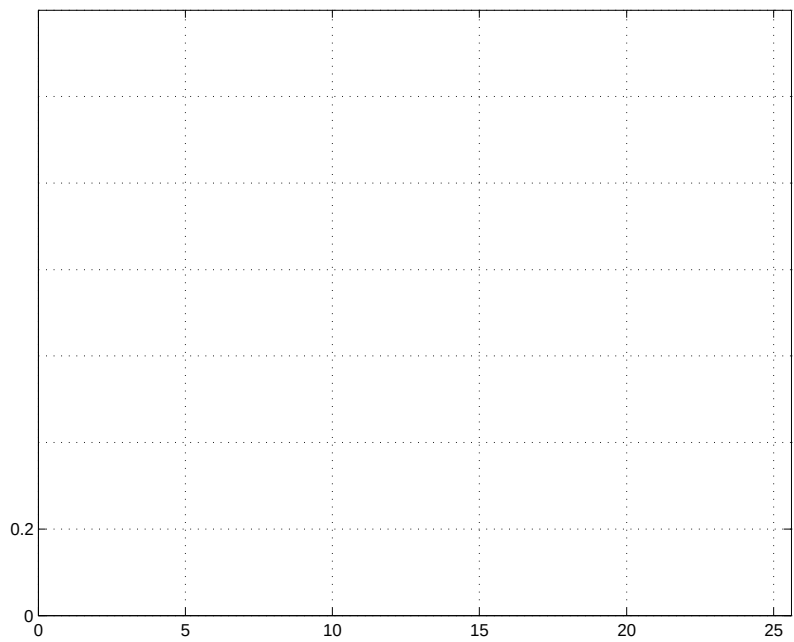


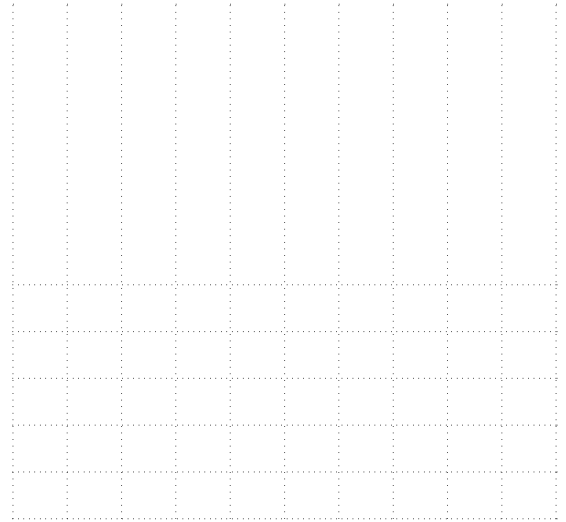
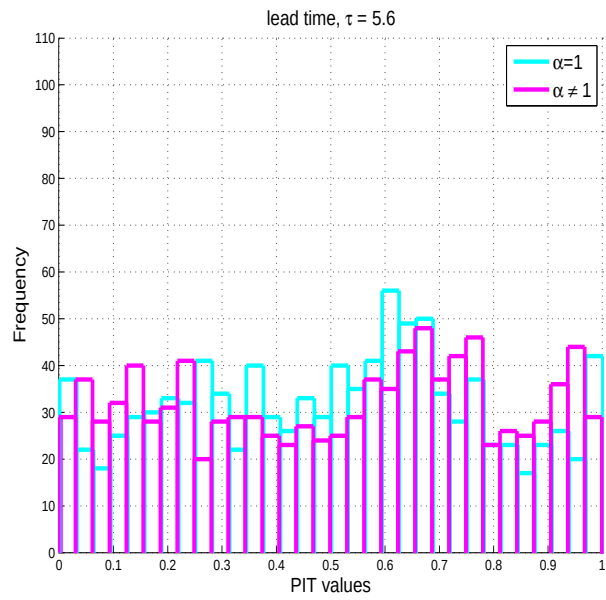


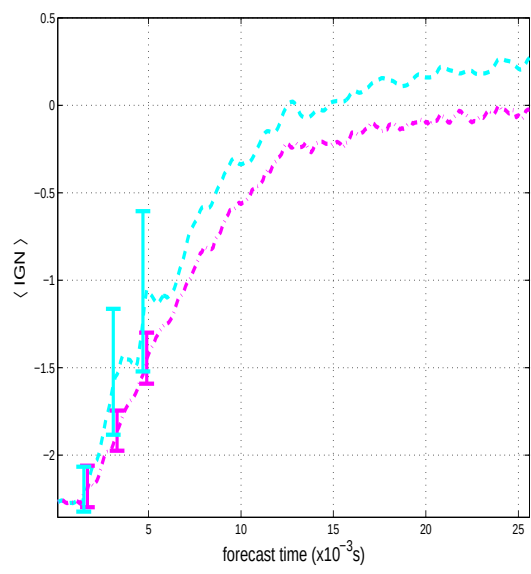
F  *Graph of the climatology of the circuit estimated from data. Its entropy is 2.15, which is greater than the entropies shown in figure 1.*

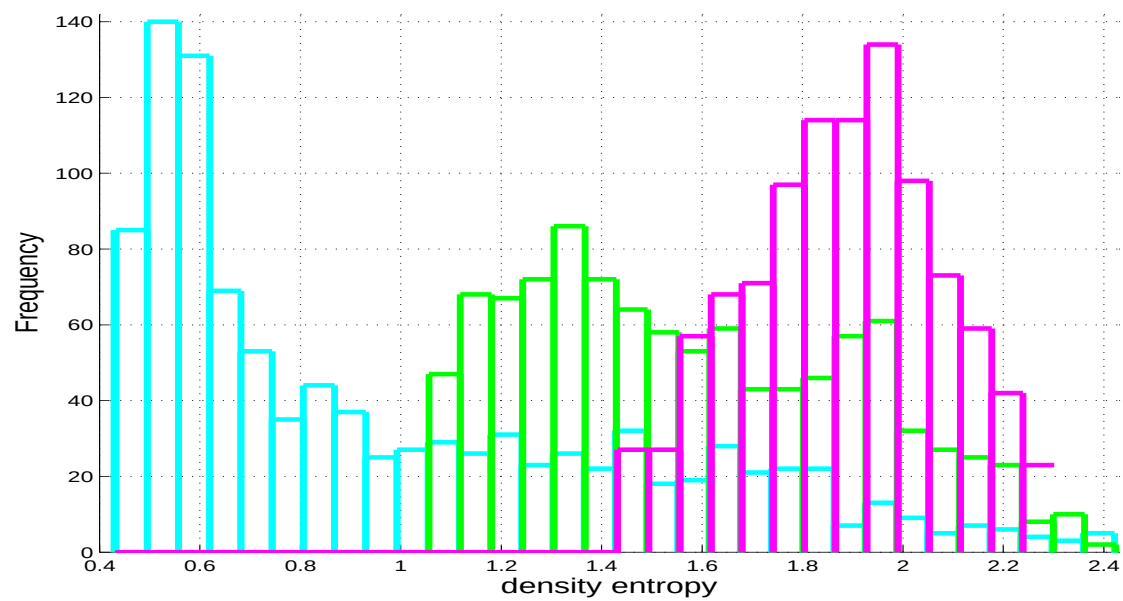












annon CE tor Co un cat on n t, pr s ac ro no s vo t ro

$$\mathbf{t} \, x \qquad \mathbf{t}^{-1} \, _1 \{ \, _1 \, x \, \} \qquad \text{It } \mathbf{t} \, \text{ n o ows } \mathbf{t} \, \text{ at}$$

$$\subseteq \sum_{\mathbf{t}=1}^{\mathbf{T}} \mathbf{t} \big[\mathbf{t} \{ \mathbf{s}^{-1} \, x_{\mathbf{s}} \} \big]$$

 t. r m a b at ast anot.  r p □ an p su.   t at